

What remains possible after each kind of view?

Fresh evidence can still be redundant; calibration can change what the same view identifies.

	Sum view	Changed view	Unknown wiring	Known reference
	sum = 1	difference = 1	both views	reference = left
Left · ordinary				
Right · ordinary				
Left · swapped				
Right · swapped				
	2 modeled objects remain	1 modeled object remain	2 modeled objects remain	1 modeled object remain
	 consistent	 ruled out by data	 excluded by assumption	

Exact enumeration · noiseless two-pixel toy

Source: [observation-horizon/results.json](#). Identification is conditional on the declared candidate worlds and instrument assumptions.